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## Comparative Analysis of the Vocal Repertoire of Eulemur: A Dynamic Time Warping Approach

This is the author's manuscript						
Original Citation:						
Availability:						
This version is available http://hdl.handle.net/2318/1529037 since 2016-02-15T14:53:15Z						
Published version:						
DOI:10.1007/s10764-015-9861-1						
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# UNIVERSITÀ DEGLI STUDI DI TORINO

This is an author version of the contribution published on:

Gamba, Marco; Friard, Olivier; Riondato, Isidoro; Righini, Roberta; Colombo, Camilla; Miaretsoa, Longondraza; Torti, Valeria; Nadhurou, Bakri; Giacoma, Cristina Comparative Analysis of the Vocal Repertoire of Eulemur: A Dynamic Time Warping Approach INTERNATIONAL JOURNAL OF PRIMATOLOGY (2015) DOI: 10.1007/s10764-015-9861-1

The definitive version is available at: http://link.springer.com/content/pdf/10.1007/s10764-015-9861-1

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17	Word count:
18	Keywords: vocal communication, true lemurs, species-specific differences, acoustic
19	analysis, unsupervised classification, cluster analysis.

#### 21 ABSTRACT

22 The diversity of qualitative approaches and analytical methods has often undermined 23 comparative research on primate vocal repertoires. The purpose of the present work is 24 to introduce a quantitative method based on dynamic time warping to the study of 25 repertoire size in *Eulemur* spp. We obtained a large sample of calls of *E. coronatus*, 26 E. flavifrons, E. fulvus, E. macaco, E. mongoz, E. rubriventer and E. rufus, recorded 27 between 1999 and 2013 from captive and wild lemurs. We inspected recordings 28 visually using spectrograms, then cut and saved high-quality vocal emissions to single 29 files for further analysis. We extracted the acoustic features of all vocalizations of a 30 species using the Hidden Markov Model toolkit, an application of dynamic time 31 warping, then compared cepstral coefficients (a feature widely used in automatic 32 speaker recognition) pairwise. We analysed the results using Affinity Propagation 33 clustering. We found that Eulemur species share most of their vocal repertoire but 34 species-specific calls determine repertoire size differences. Repertoire size varied 35 from 9 and 14 vocalisation types among species, with a mean of 11. Group size is 36 thought to favour the evolution of vocal complexity at the species level but our results 37 suggest that this relationship should be reconsidered, as *Eulemur rubriventer* has the 38 largest vocal repertoire but shows a relatively small average group size when 39 compared to congeneric species.

#### 41 INTRODUCTION

42

43 Vocal repertoires provide essential information to the study of how communication 44 systems evolve (Maynard Smith and Harper 2003). For example, studies of nonhuman 45 primate vocal communication have provided valuable contributions to the debate 46 about the basis for the evolution of language in humans (Dunbar 2009). Nonhuman 47 primate vocal repertoire size correlates with time spent grooming and with group size 48 (McComb and Semple 2005), providing support for the theory that the complexity of 49 human language has gradually evolved with the increase of social complexity 50 (Dunbar 2009). However, comparative studies of repertoire size are often undermined 51 by two factors. First, vocal repertoire data are derived from studies using different 52 methods (McComb and Semple 2005). Second, identification of the signal categories 53 have traditionally relied on human observers' assessment of differences among 54 vocalizations, and are thus subject to individual criteria. Although multivariate 55 techniques have demonstrated that such categories may be appropriate (e.g. Range 56 and Fischer 2004; Gamba and Giacoma 2007; Maretti et al. 2010; Fuller 2014), 57 human assessment of vocalization types may reflect differences perceived by humans 58 but not necessarily by the species (Green 1975; Hauser 1996; Fuller 2014).

59

New methodologies in the study of acoustic communication allow standardization across large datasets with limited assumptions (Clemins *et al.* 2006). These methods provide researchers with computer tools for exploring large databases without the disadvantages of subjective *a priori* classification, and are often referred to as 'unsupervised' (Stowell and Plumbley 2014; Kogan and Margoliash 1998; Stathopoulos *et al.* 2014). Among the many methods (Garcia and Reyes Garcia 2003; Koolagudi *et al.* 2012), some used for automatic speech recognition, such as dynamic 67 time warping, are increasingly used to investigate animal communication. Dynamic 68 time warping has been useful for the classification of animal sounds in amphibians 69 (Chen et al. 2012), birds (Anderson et al. 1996; Trawicki et al. 2005; Clemins and 70 Johnson 2006; Ranjard and Ross 2008; Tao et al. 2008), marine mammals (Brown 71 and Miller 2007), and primates (Riondato et al. 2013). These methods can be used to 72 investigate the vocal repertoire across populations and species (Mercado III and 73 Handel 2012; Ranjard et al. 2010) and improve our ability to make inferences about 74 the evolution of human language (Fedurek and Slocombe 2011). Although 75 unsupervised classification cannot guarantee to classify calls in a way that is 76 meaningful to animals, it does ensure quantitative objective classification (Pozzi et al. 77 2010).

78

79 Due to their unique evolutionary history, lemurs are important subjects for 80 comparative studies of vocal communication and may provide insights into the 81 selective pressures that may have linked social and vocal complexity (Oda 2009). 82 True lemurs (Eulemur spp.) are conspicuously vocal and that their vocal repertoire 83 comprises low-pitched and high-pitched sounds (Petter and Charles-Dominique 1979, 84 Macedonia and Stanger 1994; Gamba and Giacoma 2005). The presence of various 85 call variants and combinations has also been demonstrated qualitatively (Macedonia 86 and Stanger 1994). Previous studies showed that vocal repertoire may differ between 87 species in Eulemur fulvus (Paillette and Petter 1978), E. mongoz (Curtis 1997), E. 88 macaco (Gosset et al. 2001) and E. coronatus (Gamba and Giacoma 2007).

89

90 The aim of this study was to investigate objectively the vocal repertoire across
91 *Eulemur* species to understand whether different species show different repertoire size

92 and vocalization types. We used an algorithm based on dynamic time warping to 93 assess sound similarity (Ranjard et al. 2010). We then applied cluster analysis to 94 identify groups of similar calls. To understand whether vocal repertoire size differs 95 across Eulemur species we applied the same analytical process to datasets for 96 different species, including the brown lemur (E. fulvus), the mongoose lemur (E. 97 mongoz), the black lemur (E. macaco), and the crowned lemur (E. coronatus), whose 98 repertoires were investigated in previous studies. We also analysed three species that 99 were not included in previous quantitative vocal repertoire studies: the red-bellied 100 lemur (E. rubriventer), the rufous brown lemur (E. rufus), and the blue-eyed black 101 lemur (E. flavifrons). Qualitative studies of Eulemur species have shown a degree of 102 similarity in the acoustic structure of the calls but shed little light on the quantitative 103 evaluation of similarities and differences, and suffered from subjective identification 104 of the call types (Macedonia and Stanger 1994; Gamba and Giacoma 2005). No 105 previous study has combined, to our knowledge, the study of lemurs' vocal repertoire 106 across different species using a quantitative unsupervised methodology.

107

108 We tested whether or not our unsupervised analyses identified the same vocalization 109 types as previously described. Human sound recognition mechanisms are robust 110 against noise changes and integrate many factors, resulting in accurate low-level 111 acoustic classification. Humans can differentiate calls as discrete types when an 112 unsupervised program, and possibly other species, would recognize a single type 113 (Hauser 1996; Lippmann 1997). We, therefore, predicted that unsupervised clustering 114 would find fewer vocalization types than previous studies. We also predicted that 115 more variable vocalization types mask variation at a lower level, as in a clustering 116 analysis of Guinea baboon calls (Papio papio, Maciej et al. 2013). Alternatively,

117 cluster analysis may highlight variants of vocal types showing a particular contextual

118 occurrence and other types which overlap with the *a priori* classification.

119

#### 120 Methods

121

## 122 Subjects, study sites, equipment, data collection and analysis.

123 The recordings analysed for the purpose of this study were part of a large collection of 124 lemur sounds at the Department of Life Sciences and Systems Biology, University of 125 Torino. The recordings originate from various recording campaigns focused on lemur 126 vocal behaviour that took place between 1999 and 2013. They were recorded in the 127 wild and in captivity. The number of recording campaigns (hereafter corpora) and the 128 number of calls within a corpus vary with species. We only considered calls emitted 129 by adults. Detailed information about the corpora, sampling, data collection, and 130 associated references is given in the Supporting Information (Appendix S1).

131

## 132 *Clustering analyses*

133 To identify independent groupings and to visualize emerging vocal types (Nowicki 134 and Nelson 1990), we clustered vocalizations of each species on the basis of their 135 degree of dissimilarity, as measured by the pairwise comparison using dynamic time 136 warping (Ranjard et al. 2010). Detailed information about the calculation of 137 dissimilarity indices is given in the Supporting Information (Appendix S1). We used 138 the affinity propagation tool (Frey and Dueck 2007) of the apcluster package in R 139 (Bodenhofer et al. 2011; Hornik 2013). We labelled clusters with the 'representative' 140 vocalization (the 'exemplar'), which was automatically chosen during the affinity 141 propagation clustering process (see Supporting Information 1 (Appendix S2). The 142 cluster analysis used a squared negative Euclidean distance to measure dissimilarity 143 and identify clusters. This clustering algorithm is based on similarities between pairs 144 of data points. Affinity propagation clustering simultaneously considers all the data 145 points as potential cluster centers (exemplars), then chooses the final centers through 146 an iterative process, after which the corresponding clusters also emerge. Although we 147 did not define the number of clusters or the number of exemplars (Bodenhofer et al. 148 2011), the preference (p) with which a data point is chosen as a cluster center 149 influences the number of clusters in the final solution. Because affinity propagation 150 clustering does not automatically converge to an optimal clustering solution, we used 151 two external validation procedures. The first validation was based on the q-scanning 152 process (where q corresponds to the sample quantile of p, modified from Wang et al. 153 2007; see also Bodenhofer et al. 2011). We evaluated the clusters obtained using 154 different preferences using the Adjusted Rand Index (Hubert and Arabie 1985) to 155 assess the stability of successive cluster solutions (Hennig 2007). The second cluster 156 validation procedure was based on the Silhouette Index, which reflects the 157 compactness and separation of clusters in the final solution (Maciej et al. 2013). 158 When ranked and averaged between species both procedures indicated the median of 159 all the similarities between data points to be the optimal value for the preference. We 160 kept all the analysis settings the same across all datasets. We used the calls used as 161 exemplars in the final clustering solution to label the respective clusters.

162

163 A posteriori evaluation

We evaluated the agreement between the clustering analyses and the *a priori*classification using the Adjusted Rand Index (Hubert and Arabie 1985; Table 1).

167 The terminology we use in the description of the polar dendrograms refers to Drout 168 and Smith (2013). Each branch of the polar dendrogram is termed a 'branch' or a 'clade' while the terminal portion of each clade is called a 'leaf'. Two-leaved clades are 169 170 called 'bifolious', but the number of leaves in a clade is not limited. While the 171 horizontal orientation of dendrograms is irrelevant, its vertical arrangement is 172 meaningful. The vertical position of the branch points indicates how similar or 173 different they are from each other. Branches departing from the same branch point are 174 most similar and belong to the same 'level'. In the polar dendrograms, levels are 175 numbered from the center (root) to the outer ring.

176

177 We also ran a stepwise Discriminant Function Analysis (sDFA, IBM SPSS Statistics 178 21; Lehner 1996) using the acoustic parameters measured (Supporting Information 2, 179 Appendix S3, see Gamba and Giacoma 2007 for details) using Praat (University of 180 Amsterdam, Boersma and Weenink 2014). We used the sDFA to identify the weight 181 of the different parameters contributing to the clustering process, although the 182 acoustic analysis does not necessarily simulate feature extraction during the dynamic 183 time warping. We ran the sDFA with the cluster information as the grouping variable 184 to estimate how the acoustic parameters contributed to the classification of calls using 185 leave-one-out cross-validation.

186

187 **Results** 

188

189 Vocal repertoire

The cluster analysis showed variation in both the number of clusters and the
distribution of calls across clusters with species (Table 1; see Supporting Information
3, Appendix S 5).

193

*E. fulvus* vocalizations were grouped into 11 clusters (Fig. 1; Table 1). sDFA showed an overall correct classification of 84.2% (cross-validated) when we used the clusters as the grouping variable. Signal duration (on the first discriminant function) and the first formant (F1, on the second discriminant function) had the highest loads in the model (Table 2).

199 [Table. 1 HERE]

200 [Fig. 1 HERE]

*E. rufus* vocalizations grouped into 10 clusters (Fig. 2; Table 1). sDFA showed an overall correct classification of 94.7% (cross-validated) when we used the clusters as the grouping variable. Signal duration (on the first discriminant function) and minimum Fundamental frequency (MinF0, on the second discriminant function) had the highest loads in the model (Table 2).

206 [Fig. 2 HERE]

*E. rubriventer* vocalizations grouped into 14 clusters (Fig. 3; Table 1). sDFA showed a correct classification of 73.5% (cross-validated) when we used the clusters as the grouping variable. Signal duration (on the first discriminant function) and the second formant (F2, on the second discriminant function) had the highest loads in the model (Table 2).

212 [Fig. 3 HERE]

*E. mongoz* vocalizations grouped into nine clusters (Fig. 4; Table 1). sDFA showed a correct classification of 69.2% (cross-validated) when we used the clusters as the grouping variable. Signal duration and the third formant (F3) showed the highest loading values on the first and the second discriminant functions respectively (Table 2).

218 [Fig. 4 HERE]

*E. coronatus* vocalizations grouped into 13 clusters (Fig. 5; Table 1). sDFA showed a correct classification of 83.4% (cross-validated) when we used the clusters as the grouping variable. Signal duration (on the first discriminant function) and the first formant (F1, on the second discriminant function) had the highest loads in the model (Table 2).

224 [Fig. 5 HERE]

*E. flavifrons* vocalizations grouped into 10 clusters (Fig. 6; Table 1). sDFA showed a correct classification of 71.4% (cross-validated) when we used the clusters as the grouping variable. Signal duration and the first formant had the highest loads on the first two discriminant functions (Table 2).

[Fig. 6 HERE]

*E. macaco* vocalizations grouped into 10 clusters (Fig. 7; Table 1). sDFA showed a
correct classification of 82.0% when we used the clusters as the grouping variable.
Duration and F1 showed strongest correlation with the first two discriminant
functions, respectively (Table 2).

234 [Fig. 7 HERE]

#### [Table 2 HERE]

#### 236 External cluster evaluation

The agreement between the *a priori* classification and the grouping identified by the
clustering analysis was relatively low across the species, ranging 0.18 - 0.32 (Table
1).

240

#### 241 DISCUSSION

242 Our approach succeeded in categorizing vocalizations emitted by seven species using 243 dissimilarity indices. Dissimilarity indices have the advantage of being synthetic and 244 convenient but lack the detail of acoustic analysis (Maciej et al. 2013; Riondato et al. 245 2013). The discriminant model based on measures of temporal and frequency 246 parameters demonstrated that true lemurs calls can be assigned to independently 247 derived clusters identified on the basis of dissimilarity indices with a high rate of 248 correct classification. Furthermore, the accuracy achieved is in the range of that found 249 when the combination of pitch and filter features is classified a priori (Gamba and 250 Giacoma 2005; Gamba 2006).

251

## 252 *Diversity of the vocal repertoire*

True lemurs differ remarkably in their social organization and ecology (Tattersall and Sussman 1998; Mittermeier *et al.* 2008). Thus we predicted differences in their vocal communication signals, in line with previous studies (Macedonia and Stanger 1994; McComb and Semple 2005). Our results support this prediction: we found that different species show different repertoire size and vocalization types. The audiovisual identification of vocal categories varied from a minimum of 7 vocalization types in *E. coronatus* to 14 types in *E. fulvus*, *E. rubriventer*, and *E. mongoz*. The overall range obtained by the unsupervised analysis was similar, ranging 9 - 14 clusters. Thus, audio-visual identification and unsupervised classification of vocalization types gave comparable estimates.

263

264 Our results support the prediction that average group size influences vocal repertoire 265 size in part. Both audio-visual identification and unsupervised classification of 266 vocalization types provide a repertoire size estimate of 14 calls for *E. rubriventer*, an 267 estimate that is surprisingly larger than those observed for other species except E. 268 coronatus, which have group sizes is 8.4 (Kappeler and Heymann 1996), while E. 269 rubriventer has a mean group size of just 3 (Overdorff 1996) or 3.2 (Kappeler and 270 Heymann 1996). E. mongoz have a similar average group size of 3.0-3.5 (Kappeler 271 and Heymann 1996; Nadhurou et al. 2015) and show a repertoire size of 9 calls. 272 Several authors have suggested a relationship between a species' social organization 273 and its communication, proposing that an egalitarian social structure or stable social 274 groups may favor diversity in communication signals (Mitani 1996). E. rubriventer is 275 the only species we studied to have a stable, pair-bonded group structure (Tecot 276 2008). The other species live in one-male, multi-female groups or multi-male, multi-277 female groups (Fuentes 2002). The social organization in E. mongoz varies between 278 populations, and includes both pair bonding and one-male, multi-female groups 279 (Fuentes 2002). The larger distribution of E. rubriventer may also influence the 280 diversity of vocal communication, as may the fact that we included only captive E. 281 rubriventer in the analysis. However, vocal repertoire appears to be consistent across 282 captive, wild-caught individuals (Colombo, unpublished data), suggesting that other 283 factors may have a stronger effect than the distribution range size. The strong 284 relationships between repertoire size and stable social organization have been 285 proposed for facial expressions (Preuschoft and van Hooff 1995) and the rate of vocal 286 emissions (Mitani 1996), and further studies are needed to clarify whether pair-287 bonding also 'places a selective premium' (Mitani 1996, p. 246) on vocal repertoire 288 size. In support of this proposal, pair-bonding is considered a key factor favoring the 289 convergent evolution of complex singing displays (Geissmann 2000; Torti et al. 2013) 290 in the 'singing primates' (Indri indri, Tarsius spp., Presbytis spp., and Hylobates spp., 291 Haimoff 1986; Indri indri, Bonadonna et al. 2014).

292

293 We predicted that the unsupervised procedure would recognise a lower number of 294 vocalization types. This was true for *Eulemur fulvus* (11 in the unsupervised analysis 295 versus 14 in the audio-visual a priori assessment), E. mongoz (9 vs. 14), E. rufus (10 296 vs. 12) and E. macaco (10 vs. 11). The repertoire estimate derived from a previous 297 study of *E. macaco* (N = 13; Gosset *et al.* 2001) exceeds both that observed during the 298 reassessment process (N = 10) and the result of the cluster analysis (N = 10). 299 Although the calls in our sample may be incomplete, we suspect that this discrepancy 300 arose due to the different criteria used to assess vocalization types in these studies.

301

302 Our prediction that the unsupervised procedure would recognise a lower number of 303 vocalization types was not supported in two cases: *Eulemur coronatus* (13 304 unsupervised versus seven audio-visual vocal types) and *E. mongoz* (14 vs. nine). In 305 both cases, the unsupervised procedure recognized more than one type of alarm call. 306 Previous studies of these species estimated a vocal repertoire size of 15 vocalizations for *E. mongoz* (nine validated using sDFA; Nadhurou et al. 2015) and 10 vocalizations for *E. coronatus* (all validated using DFA, Gamba and Giacoma 2007). It is clear that different methods led to different estimates, but interesting that, in principle, dynamic time warping allows the identification of vocalization types using a smaller number of calls than sDFA. Whether these differences in vocal repertoire size reflect different arousal states or contexts is an interesting direction for future research.

314

#### 315 *Cluster versus* a priori *classification*

316 Agreement between the clustering process and the *a priori* criteria was low, with 317 values of the Adjusted Rand Index ranging between 0.18 (in E. rubriventer) and 0.32 318 (in E. coronatus and E. macaco and E. rufus). This supports the prediction that 319 unsupervised clustering of the vocalizations would not find the vocalization types 320 identified in previous studies. However, despite the differences with the *a priori* 321 classification, the clusters obtained using dynamic time warping-generated 322 dissimilarity indices revealed a remarkable potential for grouping calls on the basis of 323 acoustic measurements of different parameters. Among the parameters, duration 324 showed the heaviest loadings on the first discriminant function. Thus, the 325 mismatching between the *a priori* classification and cluster analysis is in line with the 326 suggestion that humans tend to recognize as discrete vocal types sounds that may be grouped into a single type when perceived by other species or classified by 327 328 quantitative analyses (Hauser 1996).

Both duration and formants contributed to the identification of clusters in almost all the species considered. Formants are known to be crucial for the identification of vocalization types (Gamba 2014; Gamba and Giacoma 2007; Giacoma *et al.* 2011) and have the potential to provide listeners with individual and species-specific cues (Gamba *et al.* 2012a).

335

336 Snorts, clicks, and hoots were not selected as cluster representatives and were often 337 grouped with different vocalization types to form fairly dishomogeneous clusters. 338 This result is consistent across the species and is in line with previous data which 339 suggest that low-pitched calls may be part of a graded system more than discrete 340 emissions (Gamba and Giacoma 2007). Identifiable vocalization types are common, 341 but calls with intermediate acoustic structure may also occur and may be either 342 'oversplit' by human listeners or not recognized as discrete by the unsupervised 343 methodology we adopted. Eulemur low-pitched calls (grunts, clicks, grunted hoots, 344 hoots, snorts, and possibly long grunts) are usually classified as contact calls (Rendall 2000; Gamba and Giacoma 2005; 2007; Gamba et al. 2012a; 2012b; Pflüger and 345 346 Fichtel 2012). These low-pitched signals, especially grunts, are the most frequently 347 emitted call type in Eulemur (Gamba and Giacoma 2005; Gamba et al. 2012a; Pflüger 348 and Fichtel 2012). However, whether acoustic variation in low-pitched signals plays a 349 role in encoding information other than emitter position is still unclear (Pflüger and 350 Fichtel 2012).

351

The context of call emission is a powerful indicator of their social function and may provide crucial information to the investigation of acoustic structure (Rendall *et al.*  354 1999; Gros-Louis *et al.* 2008). Future studies are necessary to explore the contextual
355 variation of the vocalization types, how the occurrence of vocal signals relates to their
356 acoustic structure, and how this information can be integrated into unsupervised
357 analyses.

358

359 Although there was low agreement between cluster analysis and a priori classification, distinct types of grunts and/or grunted hoots emerge in all species. In 360 361 addition, grunts emitted by *E. coronatus* are identified as three different types. Long 362 grunts, which are reported to denote contexts of disturbance and potential territorial 363 predation, or are emitted during locomotion (Gamba and Giacoma, 2005; 2007; 364 Pflüger and Fichtel 2012), occur in Eulemur mongoz and E. fulvus. Associations 365 between low-pitched calls and tonal calls emerged as distinct clusters (grunt-tonal 366 calls, long grunt-tonal calls) in all species except E. rufus, and have been reported for 367 many species (Macedonia and Stanger 1994).

368

369 Our findings support the prediction that variation in particular vocal types may mask 370 variation at a lower level, in agreement with a study of Guinea baboon calls (Maciej et 371 al. 2013). In baboon calls, variation in screams was stronger than for other 372 vocalization types. In five of six *Eulemur* species, we found that screams represented 373 more than one (usually homogeneous) cluster (Eulemur flavifrons did not emit 374 screams in the same situation in which other species emitted them). In *Eulemur fulvus* 375 and E. rufus, we identified three clusters of territorial calls, while alarm calls formed 376 three clusters in E. coronatus and five clusters in E. flavifrons. The fact that cluster 377 analysis identified more than one cluster of alarm calls, screams, and territorial calls indicates variability that has not been reported in previous studies (Macedonia and
Stanger 1994; Gamba and Giacoma 2007). These results represent an operationally
useful indication for future studies, which may link vocal variation with factors such
as level of arousal, social interactions or audience composition (Fichtel and
Hammerschmidt 2002; Stoeger *et al.* 2011; Slocombe and Zuberbühler 2007; Clay
and Zuberbühler 2012).

384

385 In conclusion, dynamic time warping appears to be a promising method for deepening 386 our knowledge of how lemurs encode information in their vocal signals, and allows 387 the objective identification of vocalization types. We envisage the use of unsupervised 388 classification in different circumstances, including field studies. For example, various 389 researchers report that the classification of calls to be used in playback experiments is 390 particularly challenging. Acoustic analysis may reveal that recorded calls may in fact 391 be different signals (Rendall et al. 1999). Researchers can face the problem of 392 classifying calls in different groups when in the field. In these situations, the 393 unsupervised classification of a small number of calls can be very helpful to provide 394 the investigator with an interpretable quantitative analysis, which may result in 395 improved experimental design and aid in the evaluation of the results (Seiler et al. 396 2013).

397

## 398 Acknowledgements

This research was supported by the Università di Torino. Grants from the ParcoNatura Viva—Centro Tutela Specie Minacciate supported recordings in captivity in

the European Zoos and at the PBZT (Antananarivo, Madagascar). We thank Dr. 401 402 Cesare Avesani Zaborra, Dr. Caterina Spiezio, Gilbert Rakotoarisoa, Jules Medard, 403 Haingoson Randriamialison, Hajanirina Ramino, Fanomezantsoa Andrianirina, Yves 404 Rumpler, Jean-Marc Lernould, Pierre Moisson, Sara De Michelis, Brice Lefaux, 405 Lanto and Mamatin for their help and logistic support. We also thank Caroline 406 Harcourt, Carlo Comazzi and Emilio Balletto for their comments on earlier versions 407 of this manuscript. We thank the editors and two anonymous reviewers for their 408 constructive comments, which helped improving the manuscript.

409

- 410 Supporting Information Online Resource 1 (Appendix S1 and S2), Online Resource 2
- 411 (Appendix S3), Online Resource 3 (Appendix S4 and S5), and Online Resource 4
- 412 (Appendix S6) are available online.

413

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#### 708 FIGURE LEGENDS

709

710 Fig. 1 Polar dendrogram (center) showing how vocalizations of Eulemur fulvus cluster 711 together (see Supporting Information 3, Appendix S4 for a detailed description of cluster 712 topology). For each cluster, we show a spectrogram (the horizontal axis represents time; the 713 vertical axis represents frequency) of the exemplar chosen during the affinity propagation 714 process. All spectrograms are generated in Praat with the following parameters: window 715 length: 0.025 sec, time range as shown (0.25-2.50 sec); frequency range: 0-10500 Hz; 716 dynamic range: 35-45 dB. The bar indicates 1 sec duration. Exceptions are indicated as 717 follows: \* for 1.25 sec, \*\* for 1.50 sec, \*\*\* for 2.50 sec. Values in parentheses indicate the 718 percentage of the exemplar's vocalization type in a cluster. Additional information is given in 719 Supporting Information 3 (Appendix S4 and S5) and 4 (Appendix S6).

720 Fig. 2 Polar dendrogram (center) showing how vocalizations of Eulemur rufus cluster 721 together (see Supporting Information 3, Appendix S4). For each cluster, we show a 722 spectrogram of the exemplar chosen during the affinity propagation process. All spectrograms 723 are generated in Praat with the following parameters: window length: 0.025 sec, time range as 724 shown (0.25-2.00 sec); frequency range: 0-10500 Hz; dynamic range: 35-45 dB. The bar 725 indicates 1 sec duration. Exceptions are indicated as follows: \* for 1.25 sec, \*\* for 1.75 sec, 726 \*\*\* for 2.00 sec. Values in parentheses indicate the percentage of the exemplar's vocalization 727 type in a cluster. Additional information is given in Supporting Information 3 (Appendix S4 728 and S5) and 4 (Appendix S6).

729 Fig. 3 Polar dendrogram (center) showing how vocalizations of *Eulemur rubriventer* cluster 730 together (see Supporting Information 3, Appendix S4). For each cluster, we show a 731 spectrogram of the exemplar chosen during the affinity propagation process. All spectrograms 732 are generated in Praat with the following parameters: window length: 0.025 sec, time range as 733 shown (0.25-0.75 sec); frequency range: 0-10500 Hz; dynamic range: 35-45 dB. The bar 734 indicates 1 sec duration. Values in parentheses indicate the percentage of the exemplar's 735 vocalization type in a cluster. Additional information is given in Supporting Information 3 736 (Appendix S4 and S5) and 4 (Appendix S6).

737

Fig. 4 Polar dendrogram (center) showing how vocalizations of *Eulemur mongoz* cluster together (see Supporting Information 3, Appendix S4). For each cluster, we show a spectrogram of the exemplar chosen during the affinity propagation process. All spectrograms are generated in Praat with the following parameters: window length: 0.025 sec, time range as shown (0.25-1.25 sec); frequency range: 0-10500 Hz; dynamic range: 35-45 dB. The bar

indicates 1 sec duration. Exceptions are indicated as \* for 1.25 sec. Values in parentheses
indicate the percentage of the exemplar's vocalization type in a cluster. Additional
information is given in Supporting Information 3 (Appendix S4 and S5) and 4 (Appendix S6).

747 Fig. 5 Polar dendrogram (center) showing how vocalizations of Eulemur coronatus cluster 748 together (see Supporting Information 3, Appendix S4). For each cluster, we show a 749 spectrogram of the exemplar chosen during the affinity propagation process. All spectrograms 750 are generated in Praat with the following parameters: window length: 0.025 sec, time range as 751 shown (0.25-1.00 sec); frequency range: 0-10500 Hz; dynamic range: 35-45 dB. The bar 752 indicates 1 sec duration. Values in parentheses indicate the percentage of the exemplar's 753 vocalization type in a cluster. Additional information is given in Supporting Information 3 754 (Appendix S4 and S5) and 4 (Appendix S6).

755

756 Fig. 6 Polar dendrogram (center) showing how vocalizations of Eulemur flavifrons cluster 757 together (see Supporting Information 3, Appendix S4). For each cluster, we show a 758 spectrogram of the exemplar chosen during the affinity propagation process. All spectrograms 759 are generated in Praat with the following parameters: window length: 0.025 sec, time range as 760 shown (0.25-2.50 sec); frequency range: 0-10500 Hz; dynamic range: 35-45 dB. The bar 761 indicates 1 sec duration. Exceptions are indicated as follows: \* for 1.25 sec, \*\* for 1.75 sec, 762 \*\*\* for 2.00 sec. Values in parentheses indicate the percentage of the exemplar's vocalization 763 type in a cluster. Additional information is given in Supporting Information 3 (Appendix S4 764 and S5) and 4 (Appendix S6).

765

766 Fig. 7 Polar dendrogram (center) showing how vocalizations of Eulemur macaco cluster 767 together (see Supporting Information 3, Appendix S4). For each cluster, we show a 768 spectrogram of the exemplar chosen during the affinity propagation process. All spectrograms 769 are generated in Praat with the following parameters: window length: 0.025 sec, time range as 770 shown (0.25-1.00 sec); frequency range: 0-10500 Hz; dynamic range: 35-45 dB. The bar 771 indicates 1 sec duration. Values in parentheses indicate the percentage of the exemplar's 772 vocalization type in a cluster. Additional information is given in Supporting Information 3 773 (Appendix S4 and S5) and 4 (Appendix S6).

Vocalization	E. fulvus	E. rufus	E. rubriventer	E. mongoz	E. coronatus	E. flavifrons	E. macaco
Alarm Call	0	1		0	4	5	1
Alarm Long Grunt		0		1			
Chatter	1		0	0		0	0
Click	0	0	0	1			0
Group Cohesion Call	1	1		1			
Grunted Hoot	0	1	0	1	0	2	0
Grunt	2	1	1	1	3	0	1
Grunt-Tonal Call	1	0	0	1	1	1	
Gurgle			1				
Hoot	0	0	1	0	0	0	0
Hoot-Tonal Call			2				
Long Grunt			1	1		0	1
Long Grunt-Tonal Call	1					2	1
Scream	2	3	2	1	4		5
Snort-Grunt			0				
Snort-Grunt-Tonal Call			3				
Snort	0	0	0	0			0
Territorial Advertisement Call	3	3		1			
Tonal Call-Grunt	0						
Tonal Call	0	0	3	0	1	0	1
Number of clusters	11	10	14	9	13	10	10
Adjusted Rand Index	0.27	0.32	0.18	0.24	0.32	0.32	0.25

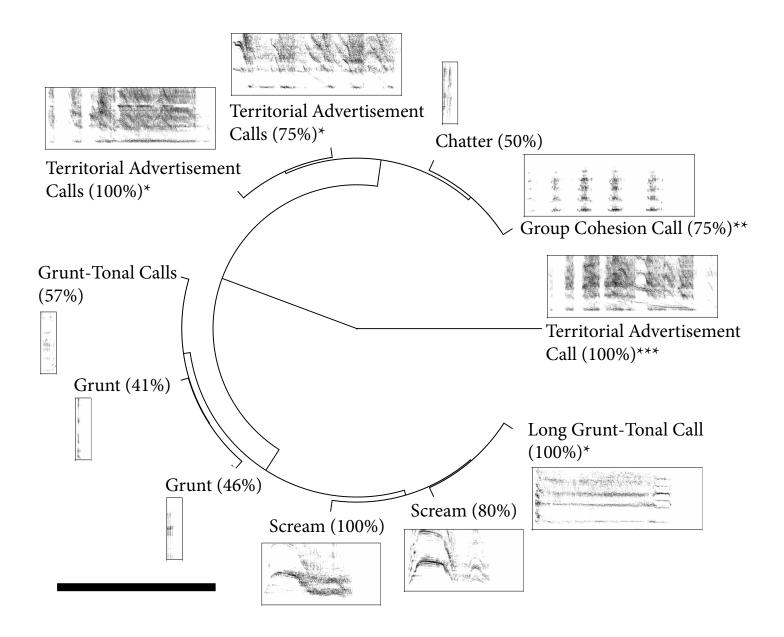
**Table 1.** Distribution of the vocalizations indicated *a priori* and as they emerged from the cluster analysis.

Table 1. Distribution of the vocalizations indicated *a priori* and as they emerged from the cluster analysis. The numbers indicate the number of exemplars chosen during the clustering analysis for that particular vocalization. Grey-shaded cells show where a particular vocalization has not been assessed during the *a priori* classification. The number of clusters indicates the total number of clusters emerged during the Affinity Propagation process and the Adjusted Rand Index quantify the agreement between the *a priori* classification and the clustering analysis.

Species	Wilks' L.	Р	CCR (%)	1 <sup>st</sup> D. f.	2 <sup>nd</sup> D. f.
E. fulvus	0.003	< 0.001	84.2	88.9% (Duration)	11.1% (F1)
E. rufus	0.006	< 0.001	94.7	98.2% (Duration)	1.0% (MinF0)
E. rubriventer	0.006	< 0.001	73.5	91.7% (Duration)	7.2% (F2)
E. mongoz	0.037	< 0.001	69.2	81.4% (Duration)	13.9% (F3)
E. coronatus	0.007	< 0.001	83.4	96.6% (Duration)	2.8% (F1)
E. flavifrons	0.011	< 0.001	71.4	84.6% (Duration)	14.1% (F1)
E. macaco	0.006	< 0.001	82.0	78.2% (Duration)	16.1% (F1)

Table 2. Stepwise discriminant analysis results for the seven Eulemur species.

Table 2. The table shows the statistical results of the seven stepwise Discriminant Function Analyses (sDFA) using temporal parameters (Duration, Ptmin, Ptmax), fundamental frequency parameters (MeanF0, MinF0, MaxF0, RangeF0, StartF0, EndF0), and formants (F1, F2, F3). The grouping variable for each sDFA was the cluster membership resulted from the Affinity Propagation clustering analysis. We reported the Wilks' Lambda values (Wilks' L.), the p-values (P), the cross-validated correct classification rate (CCR) and the variance explained by the first (1<sup>st</sup> D. f.) and the second (2<sup>nd</sup> D. f.) discriminant functions. In brackets, we also reported the parameters showing the highest load on the discriminant functions.



## Figure 2 Click here to download Figure: Gamba\_et\_al\_Fig2R2.eps

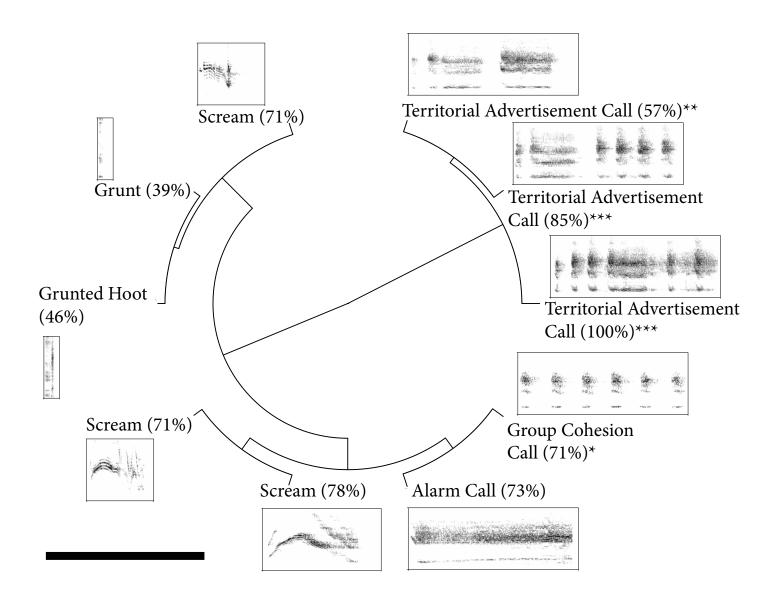
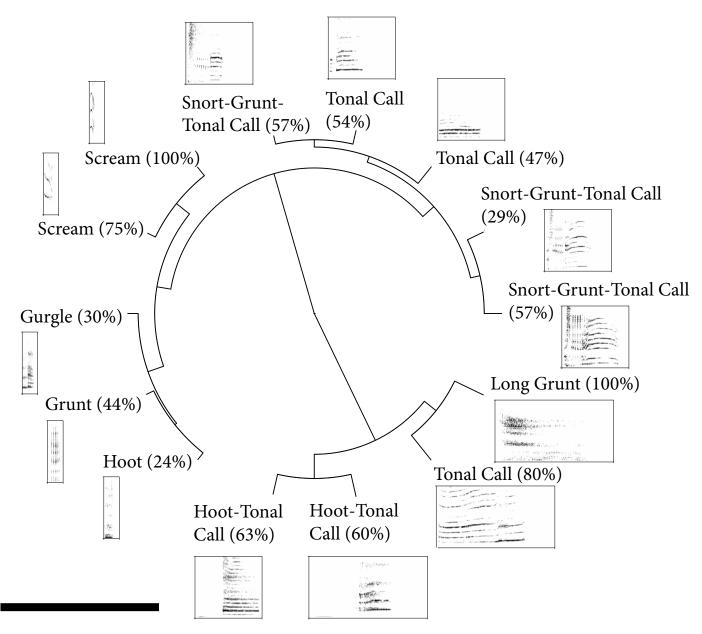
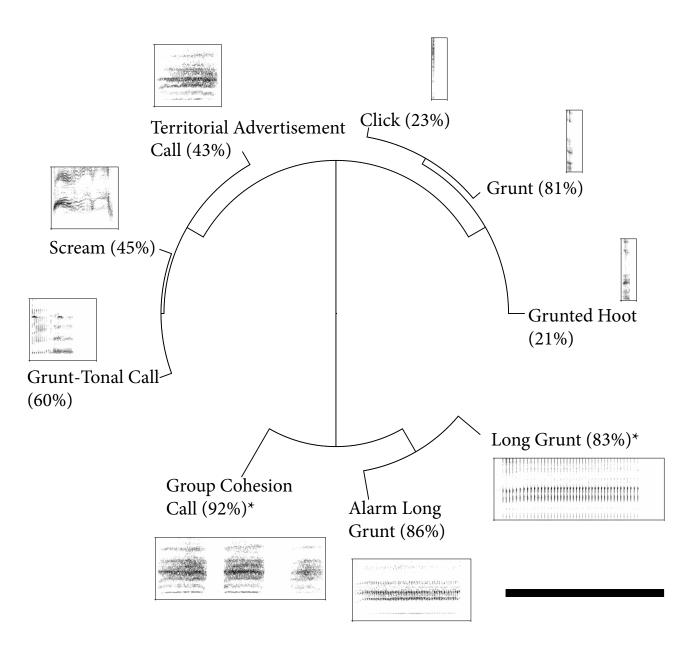
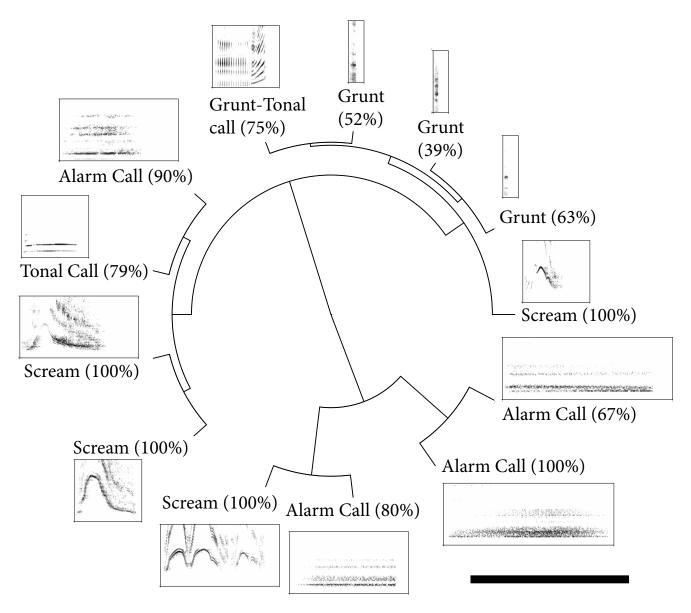


Figure 3 Click here to download Figure: Gamba\_et\_al\_Fig3R2.eps





#### Figure 5 Click here to download Figure: Gamba\_et\_al\_Fig5R2.eps



#### Figure 6 Click here to download Figure: Gamba\_et\_al\_Fig6R2.eps

