

Limits and potentialities of gridded LiDAR data in the forest context: the case of the Piemonte Region dataset



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GOAL

INDIRECT Quality Assessment of the «new» Piemonte Region LiDAR gridded dataset (DTM+DSM) and digital orthoimages: error quantification and relationship with terrain morphometry.

METHODS

TEST SET: 17 sample areas, 3 different terrain conditions: **Lowland, Hill, Mountain.**

AVAILABLE DATASETS

ICE 2009/2011 DTM and DSM

Format: grid (interpolated) with GSD = 5m
Quality: DTM level 4th; Height accuracy = ±0.3 m
 Horiz. accuracy = ± 0.3 m

RGB /VNIR digital orthos: GSD = 0.4 m

SENSORS TECHNICAL DETAILS

LiDAR sensor: LEICA LS50-II.

Digital camera: ZI-DMC

HOW CAN DATA BE VALIDATED WITHOUT GROUND TRUTH?

ERRORS QUANTIFICATION

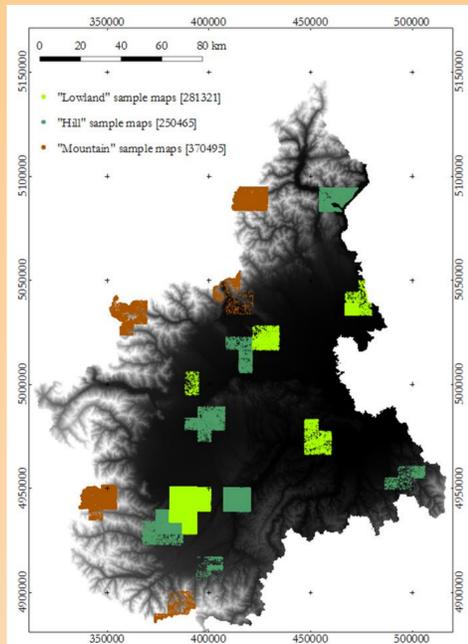
A traditional validation, based on the comparison between ground and data measurement is too expensive. But, specifically for DSMs, some indications can come from:

- investigating the occurrences of CHM (*Canopy Height Model*) negative values;
- comparing height values at the same position, if overlapping areas between adjacent tiles are present.
- Investigating co-registration level between orthoimages and DSM.

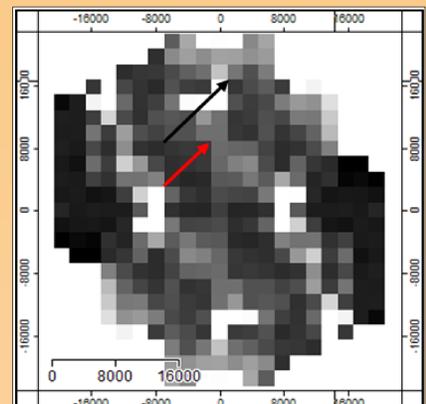
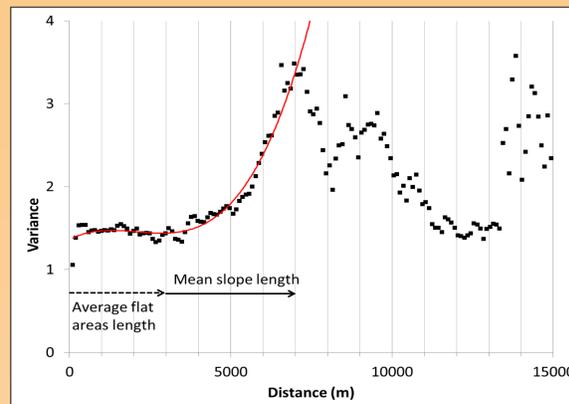
ERRORS QUALIFICATION

For **A)** and **B)** a correlation analysis was done to investigate if any relationship between errors and terrain morphometry (slope) is present.

A **geostatistical analysis** was performed by analyzing **variograms** to measure and qualify the spatial autocorrelation of errors.



A2 - CHM ERROR VARIOGRAMS



VARIOGRAM and SURFACE VARIOGRAM

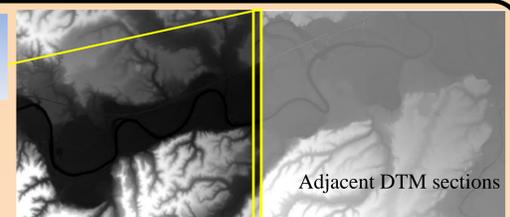
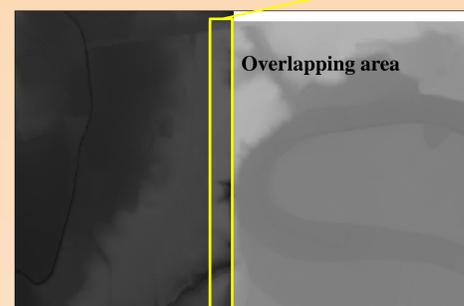
CHM errors strongly depend on topography

Variogram and surface variogram can be easily related to the actual morphometry of the area.

- Variance is low for flat areas, i.e. spatial autocorrelation of error is missing
- Variance increases while slopes tend to be steeper

B - DTM/DSM ERRORS ANALYSIS

(referred to 20% of points)

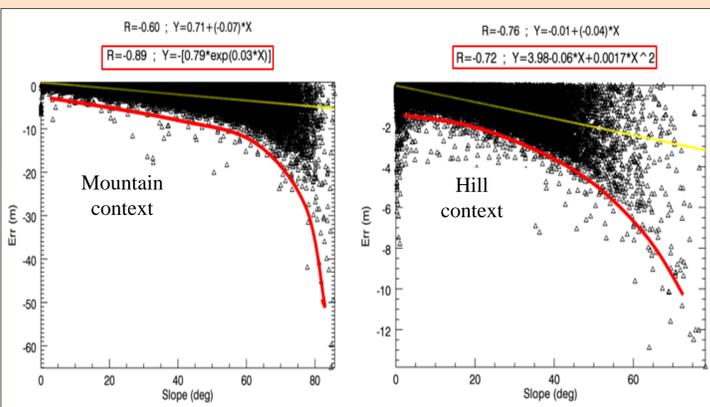


No correlation of errors with terrain morphometry was found for this type of error

Context	Data	Err > Tolerance ($\sqrt{2} \times 0.60 \text{ m}$)
Lowland	DTM	0.30%
Hill	DTM	1.80%
Mountain	DTM	17.50%
Lowland	DSM	1.70%
Hill	DSM	8.80%
Mountain	DSM	22.00%

RESULTS

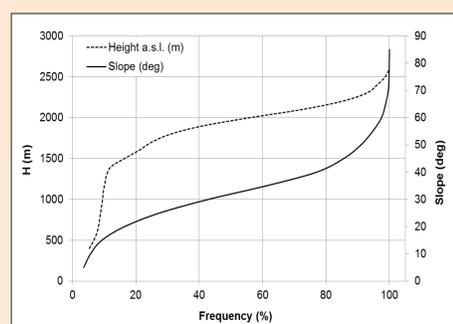
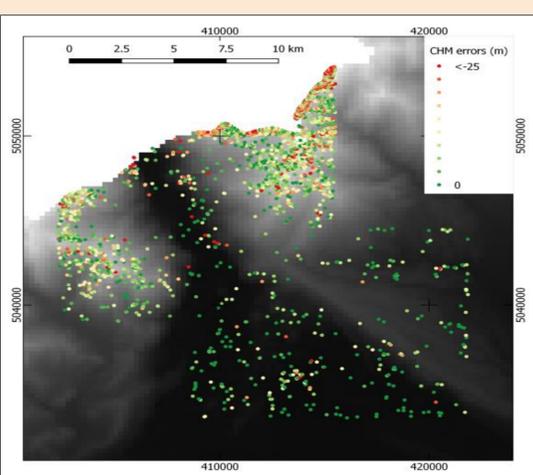
A1 - CHM ERRORS ANALYSIS (results are referred to 5% of points with CHM < 0)



Scatterplots relating CHM errors and slope steepness.

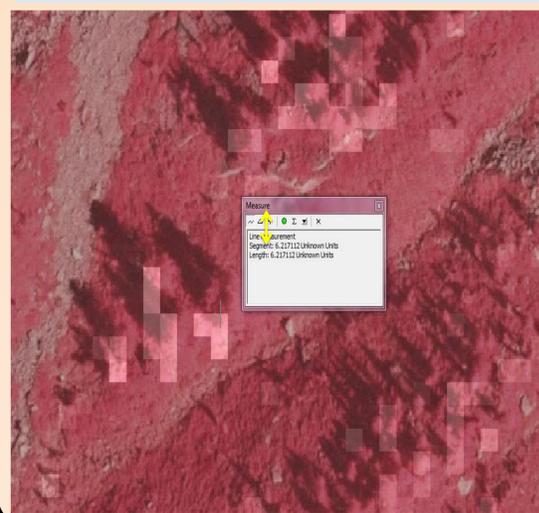
Exponential and **parabolic** regression models well fit the maximum committable error (MCE) in mountain and hill context.

CHM errors (negative) > declared tolerance ($\sqrt{2} \times 0.60 \text{ m}$)
Lowland = 0.34 % , Hill = 1.28 % , Mountain = 12.24 %



Example area (mountain) and correspondent cumulative frequency distribution for elevations and slopes.

C - DSM AND ORTHOIMAGES CO-REGISTRATION ANALYSIS



Displacements between canopies mapped from DSM and canopies mapped from orthoimages → orthoimages are not TRUE orthoimages → as many forest applications dealing with tree-line mapping often base their measurements onto aerial or satellite ortho-images this is an important issue. In fact canopy position derived from orthos, depending on the image acquisition geometry, can be shifted determining, especially in steep areas a not negligible error in the determination of the tree-line height.

CONCLUSIONS AND FURTHER DEVELOPMENTS

CHM from LiDAR acquisition proves once more to be a valuable support for forestry applications **...BUT...**

- it suffers from precision limitations especially where slopes are steep. This can determine some errors in vegetation mapping. Therefore a question is necessary: **"How and where these anomalies are more restrictive?"** → A conscious use of the data is required.
- LiDAR data and correspondent orthoimages are not perfectly co-registered. Preliminary tests shows that displacements depends on joint effects of LiDAR and image acquisition geometry. Results (i.e. tree-line mapping) obtained from these data can be not coherent → TRUE ORTHOS are required?